

CAIDAS-WORKSHOP: AI FOR SOFTWARE ENGINEERING

CODING BY DESIGN: LLM EMPOWERS AGILE MODEL DRIVEN DEVELOPMENT

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WHO ARE WE

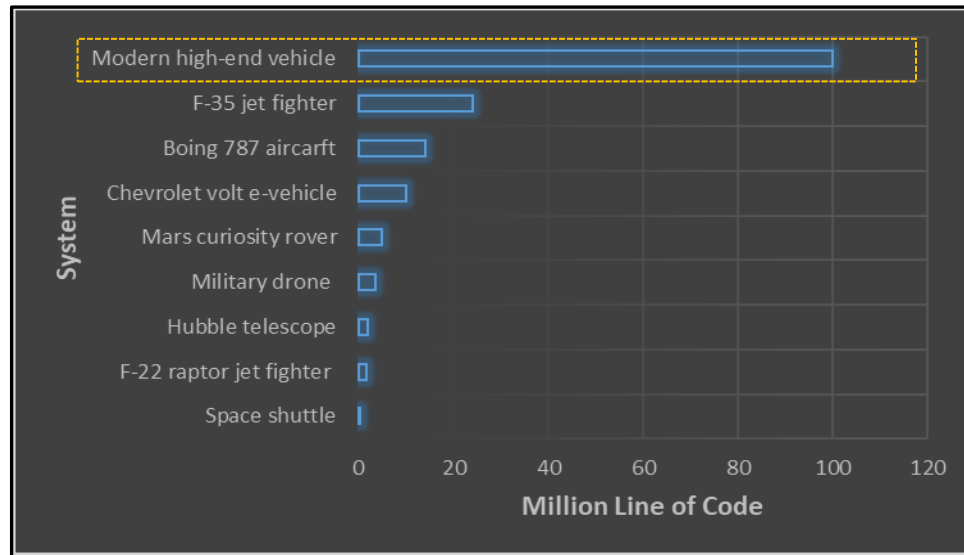


- Honda Research Institute (**HRI**) focuses on “**Innovation through Science**”
- **Three locations** (Germany, Japan, USA) ~ 200 researchers
- **Honda Global Network** with universities and research institutes
- **Advanced research** in Automotive, Robotics, Machine Learning, Optimization, and System Engineering

OUTLINE

- ❑ **MOTIVATION → SOFTWARE COMPLEXITY**
- ❑ **CHALLENGES → CODE GENERATION AND LANGUAGE AMBIGUITY**
- ❑ **APPROACH → AGILE MODEL DRIVEN APPROACH**
- ❑ **CASE STUDY → UNMANNED VEHICLE FLEET MODEL**
- ❑ **EVALUATION → GENERATED CODE BEHAVIOR AND STRUCTURE**
- ❑ **CURRENT WORK → HYPERGRAPHOS FRAMEWORK**

MOTIVATION



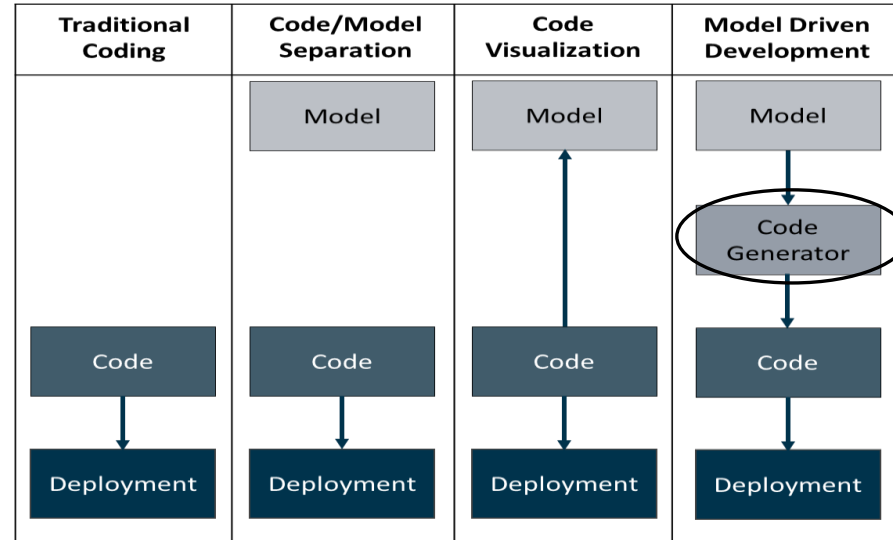
Source [freecodecamp.org]



- **Software based System Complexity** → Innovative solution to navigate system complexity
- **Large Scale System** → Agile approach to develop the system
- **Technology Transfer** → Architecting toolchain to craft precise system blueprints

CHALLENGES

➤ System Complexity

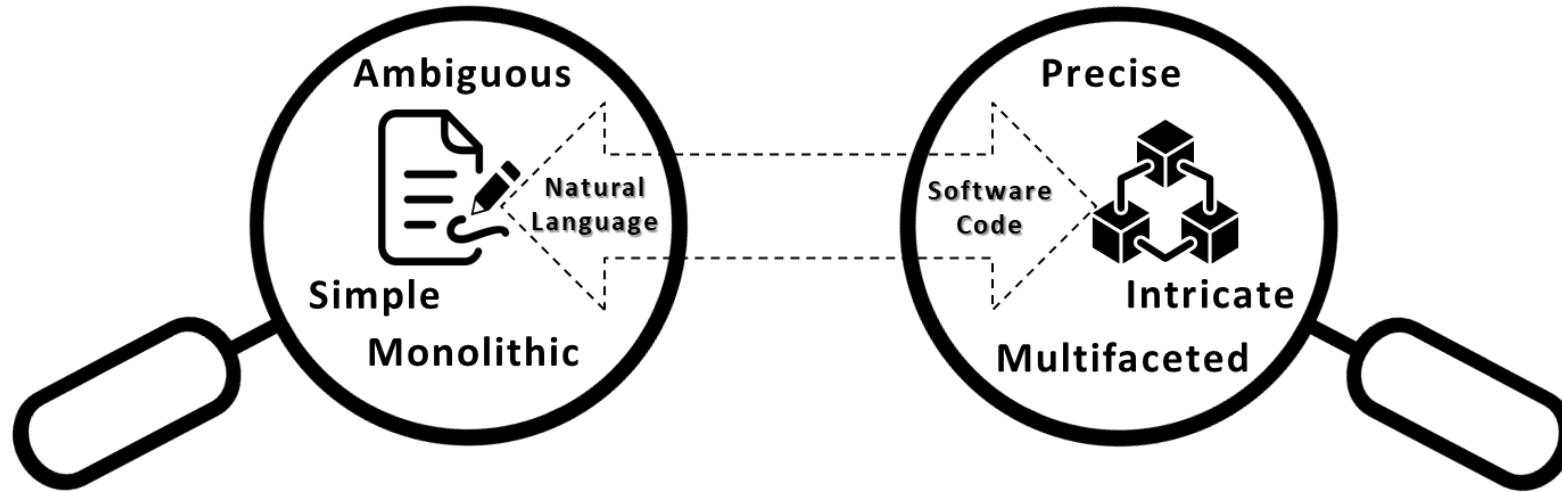


Source [Jam08]

- **Model Driven Development (MDD)** addresses the solution to manage software complexity
- Current MDD lacks **Agility** as it depends on customized code generators
- Replacing the code generator with a **Large Language Model (LLM)** enables a novel **Agile Model Driven Development (AMDD)** architecture

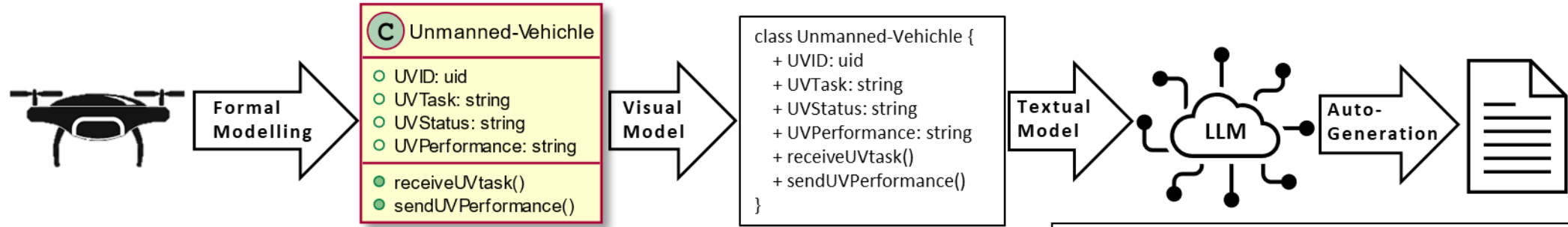
CHALLENGES

➤ Natural Language Vs Software Code

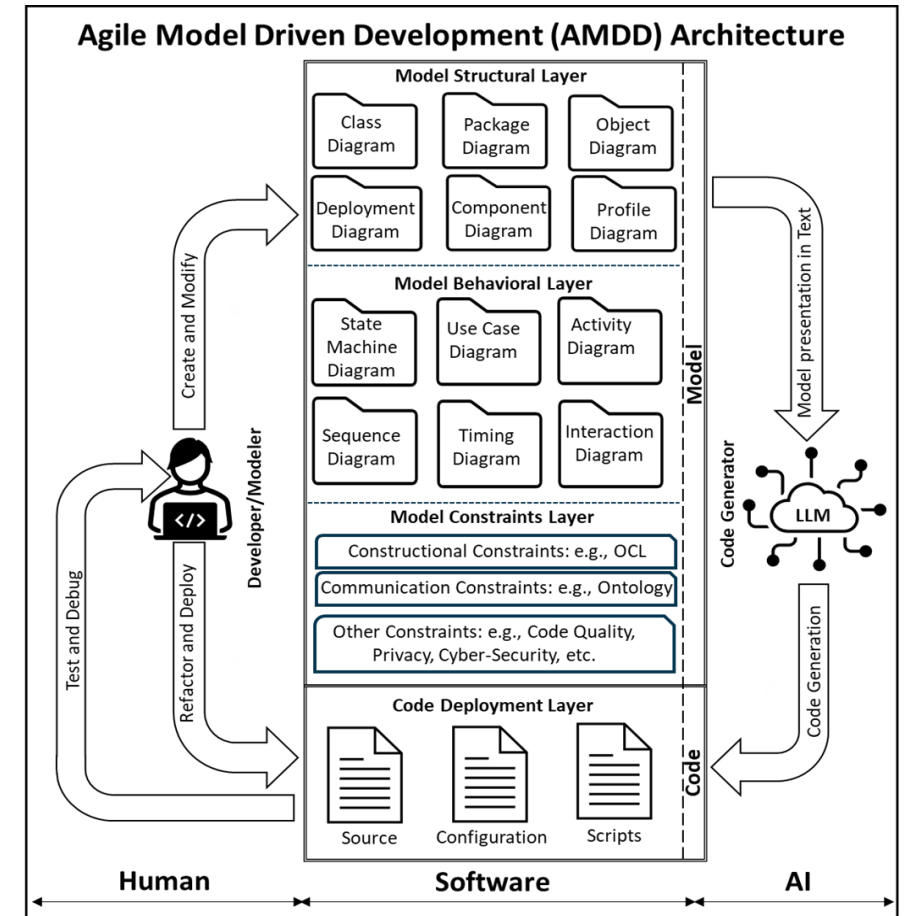


- Code Generation by LLM is commonly achieved via describing the software functionalities in **Natural Language** [SCF23]
- Generating **Deployment-Ready** software artifacts
- Generating **Intricate and Synergistically Structured** code

APPROACH



- Utilizing **Formal Modeling Languages** to sidestep ambiguity in natural language
- Using **LLM to auto-generation** of deployment-ready software
- An **AMDD** framework leveraging formal constraints to enhance model semantic clarity and reduce its ambiguity
- Advancing **Collaborative-AI** in software engineering by **Integrating Human** in the loop to refine the auto-generated code

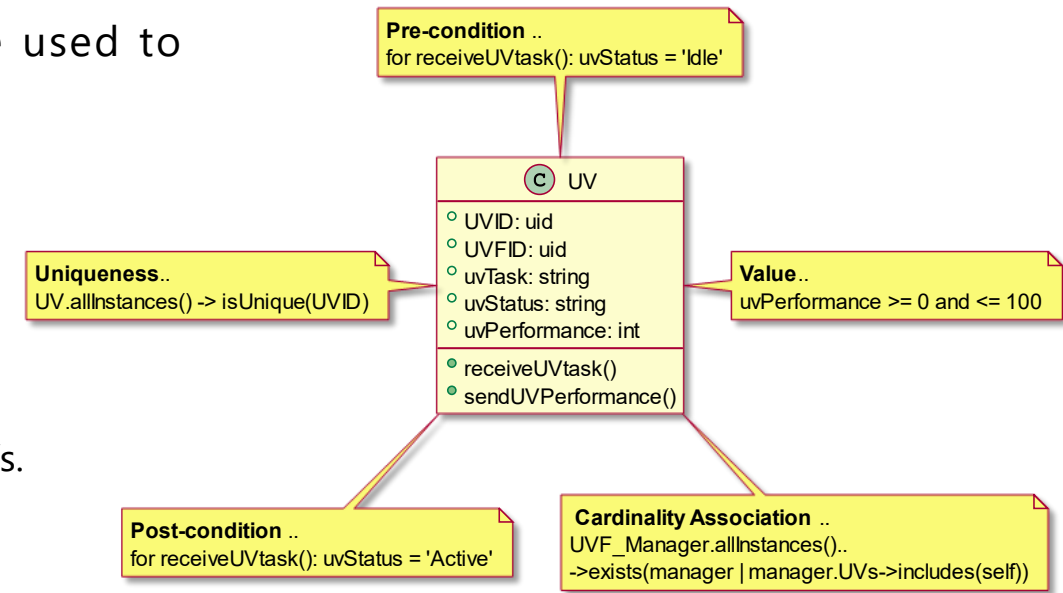


CASE STUDY: CONSTRUCTIONAL CONSTRAINTS

➤ **Object Constraints Language (OCL)** is declarative language used to specify precise constraints and fine-tune on the UML model

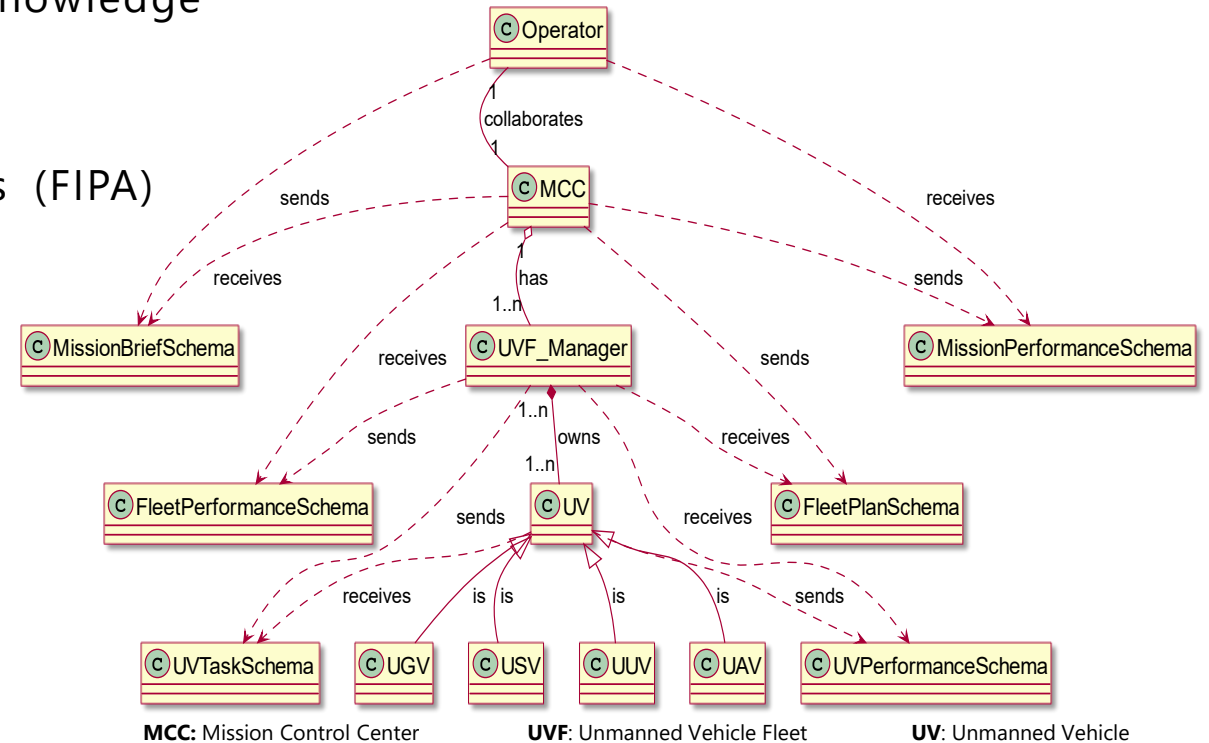
➤ Examples:

- **Uniqueness:** ensure that every class instance is unique.
→ the UV agent must have a unique identifier across MAS
- **Cardinality:** ensure the association of the class instances with each other's.
→ the UV agent is managed by the UVF-Manager
- **Value:** ensure that some of the class values are limited to certain threshold.
→ the performance value of any UV agent is within the 0 to 100 range.
- **Pre-Condition:** guarantee the state consistency of an instance before triggering the next state
→ the UV agent can only receive a new task if its current status is 'Idle'
- **Post-Condition:** mandates the new state of an instance after moving from old state
→ after a UV agent has received a new task, its status must be updated to be 'Active'



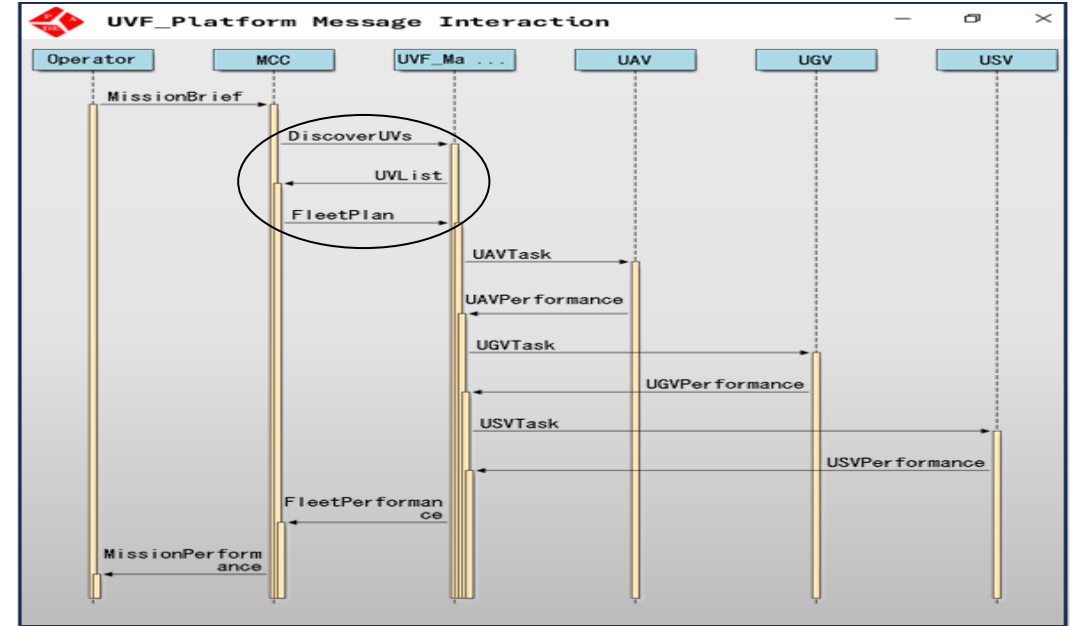
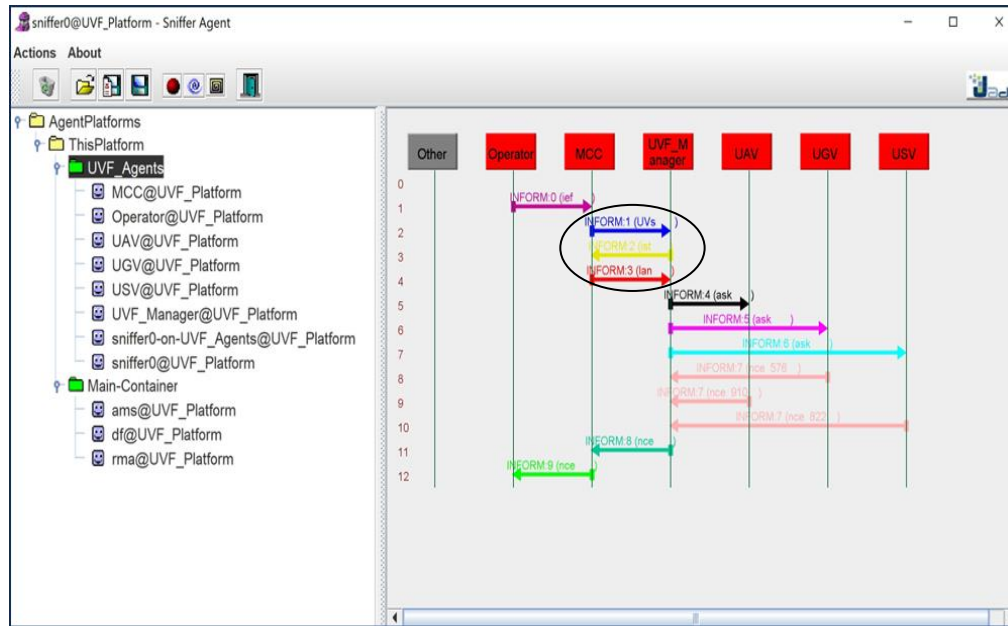
CASE STUDY: COMMUNICATION CONSTRAINTS

- **Ontology** enables the common understanding of knowledge that are exchanged
- Examples: Foundation for Intelligent Physical Agents (FIPA) ontology
 - **Concepts:** Mission-Brief → an entity within the ontology
 - **Predicates:** (agent-x) <collaborates> (agent-y) → customized relationships among agents including their communication concepts
 - **Actions:** send (schema-x) → action performed by a concept



EVALUATION: BEHAVIOURAL DYNAMIC

- Deployment in **Java** and **Python** is used to assess the code behavior



- The auto-generated code is **aligned** with the expected sequence diagram
- LLM enhanced the given activity diagram by **adding missing behavior** (Discover UVs, UVList)

EVALUATION: STRUCTURAL COMPLEXITY

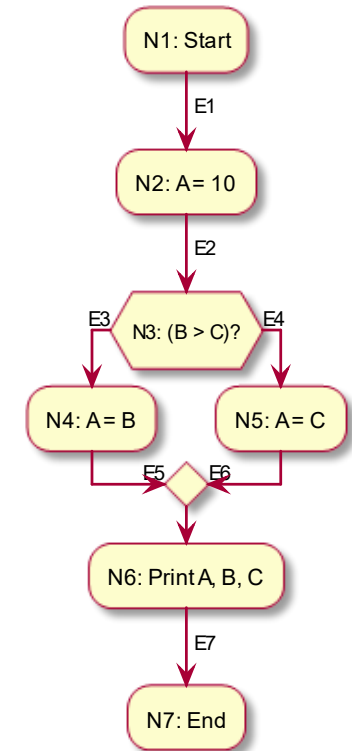
➤ Code structure is evaluated through **Cyclomatic Complexity** ($C = \text{Edges (E)} - \text{Nodes (N)} + 2 * \text{Branches (B)}$)

- $C = 1:10 \rightarrow$ Low risk
- $C = 11:20 \rightarrow$ Moderate risk
- $C = 21:50 \rightarrow$ High risk

➤ Two models with different constraints levels are used

| Generated code from a model with OCL constraints only | | | | | |
|-------------------------------------------------------|----------|-----|-------------|----|-------|
| Agent class | Operator | MCC | UVF-Manager | UV | Model |
| Edges (E) | 8 | 15 | 16 | 8 | |
| Nodes (N) | 8 | 13 | 14 | 8 | |
| Branches (B) | 1 | 1 | 1 | 1 | |
| Complexity (C) | 2 | 4 | 4 | 2 | 12 |

| Generated code from a model with OCL and FIPA-Ontology Constraints | | | | | |
|--------------------------------------------------------------------|----------|-----|-------------|----|-------|
| Agent class | Operator | MCC | UVF-Manager | UV | Model |
| Edges (E) | 12 | 22 | 23 | 12 | |
| Nodes (N) | 11 | 19 | 19 | 11 | |
| Branches (B) | 1 | 1 | 1 | 1 | |
| Complexity (C) | 3 | 5 | 6 | 3 | 17 |



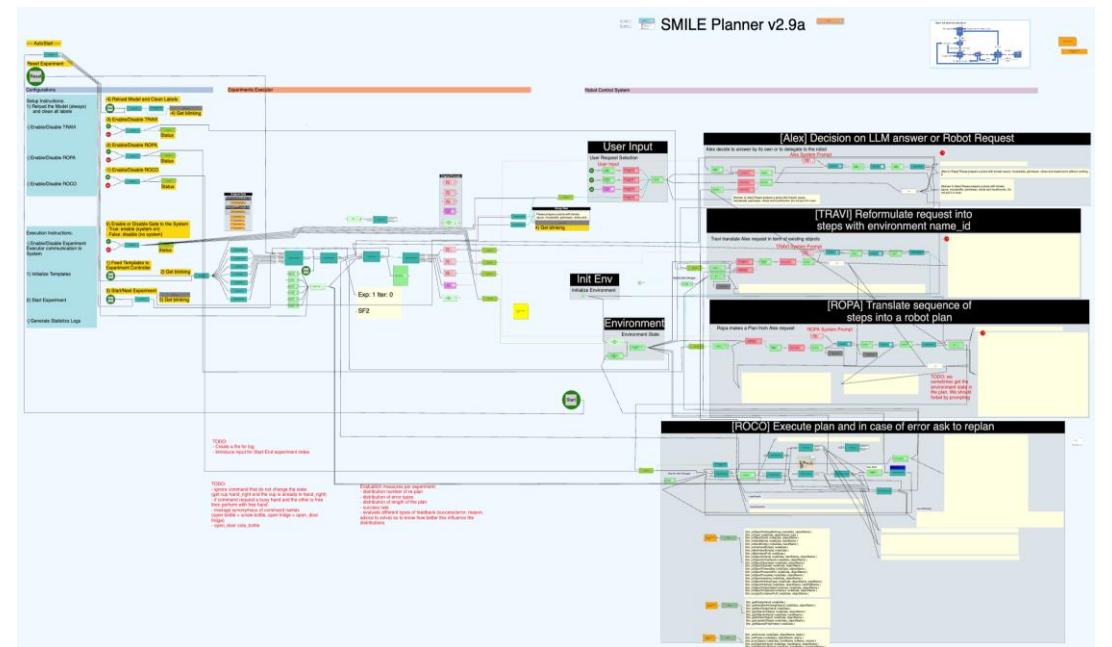
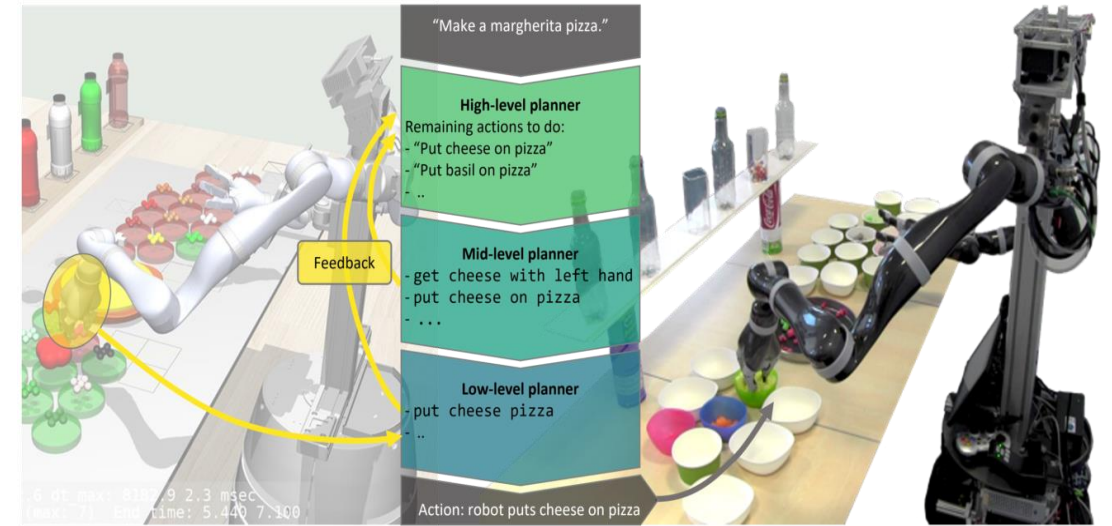
- Introducing ontology brings **additional accuracy** to the model, while it **adds to the complexity** cost
- The code complexity is still within the low risk zone, thus **more constraints can be included**

CURRENT WORK – HYPERGRAPHOS

- Objective: Cooperative planning of robot actions with LLM
- Approach: Model-based Multi-Agent System
 - ❑ 3 Main Agents (LLM):
 - Robot-Human Natural Language interface
 - Robot Motion Planner Specification Generator
 - High Level Plan Generator

➤ Features

- ❑ Real-time feedback Loop: The robot generates real-time feedback while manipulating objects.
- ❑ Corrective Feedback: On-Line Feedback used to correct/fix and problem while manipulating.
- ❑ Real world test scenarios: Tested in making pizza, cocktail and stacking cubes.



SUM UP

- LLMs can enable agile transformation of MDD, where models become the primary code artifacts.
- The natural language ambiguity challenges LLMs in generating intricate, synergistically structured code
- Mitigate challenges by employing formal language models, and enhance auto-generated code quality through consideration of diverse system constraints
- LLMs enhance auto-generated code by introducing new behaviors. However, human supervision must be essential to prevent undesired code behavior
- Employing constraints boost auto-generated code complexity, yet increases its structural clarity
- A market gap in the AMDD toolchain requires further investigation



Thank you and happy to answer your Questions?



[SBO23] Ahmed R. Sadik, Sebastian Brulin, and Markus Olhofer. "Coding by design: Gpt-4 empowers agile model driven development." *arXiv preprint arXiv:2310.04304* (2023)

[Jou23] Frank Joublin et al. "CoPAL: corrective planning of robot actions with large language models." *2024 IEEE International Conference on Robotics and Automation (ICRA)*. IEEE, 2024